

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

Claim 1 (currently amended): A robot apparatus having a behavioral model or a feeling model changed at least based on extraneous factors, comprising:

detection means for detecting extraneous states, said detection means including pressure measurement means for measuring the pressure as the extraneous state ;

storage means for storing data; ~~and~~

write control means for writing pre-set data in said storage means based on a detection signal detected by said detection means; and

means for ~~evaluating said detection signal~~ evaluating the pressure information as said detection signal from said pressure measurement means;

wherein said write control means writes ~~writing~~ said pre-set data in said storage means based on the evaluated results by said evaluation means.

Claims 2-3 (canceled)

Claim 4 (original): The robot apparatus according to claim 1 wherein said detection means includes extraneous data inputting means at which extraneous data is inputted;

said write control means writing extraneous input data to said extraneous data inputting means in said storage means.

Claim 5 (original): The robot apparatus according to claim 1 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said write control means adding characteristics information of said detection signal to said pre-set data to write the resulting signal in said storage means;

said erasure control means erasing said pre-set data added to with said characteristics information from said storage means when a pre-set condition consistent with the characteristics information holds.

Claim 6 (original): The robot apparatus according to claim 5 wherein said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 7 (original): The robot apparatus according to claim 5 wherein said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 8 (original): The robot apparatus according to claim 1 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means depending on a value of the detection signal associated with said pre-set data.

Claims 9-10 (canceled)

Claim 11 (withdrawn): A furnishing medium for furnishing a program to a robot apparatus having a behavioral model or a feeling model changed at least based on extraneous factors, said program being configured to execute processing comprising:
a detecting step of detecting extraneous states by detection means; and
a write control step of writing pre-set data in said storage means based on a detection signal detected by said detection means.

Claim 12 (withdrawn): The furnishing medium according to claim 11 further comprising:
an evaluating step of evaluating said detection signal detected by said detection means in said detection step;
said write control step writing said pre-set data in storage means based on a detection signal detected by said detection step.

Claim 13 (currently amended): A robot apparatus having a behavioral model for outputting a pre-set behavior command or a feeling model for outputting the feeling information, said robot

apparatus comprising:

detection means for detecting extraneous states, said detection means including extraneous data inputting means, wherein extraneous data is inputted by said extraneous data inputting means;

storage means for storing data; and

write control means for writing pre-set data in said storage means based on said pre-set behavior command or said feeling information, wherein said write control means writes said extraneous input data to said extraneous data inputting means in said storage means.

Claim 14 (canceled)

Claim 15 (original): The robot apparatus according to claim 13 wherein said behavioral model or said feeling model is a status transition model;

said write control means writing said pre-set data in said storage means based on a pre-set transition state of said status transition model.

Claim 16 (original): The robot apparatus according to claim 13 further comprising:

erasure control means for erasing pre-set data stored in said storage means; said erasure control means erasing said pre-set data from said storage means based on said pre-set behavior command or said feeling information.

Claim 17 (original): The robot apparatus according to claim 13 further comprising:

erasure control means for erasing pre-set data stored in said storage means;

said write control means writing said pre-set data added to with the pre-set information derived from said pre-set behavior command or the feeling information in said storage means;

said erasure control means erasing said pre-set information from said storage means when the pre-set condition associated with the pre-set behavior command holds.

Claim 18 (original): The robot apparatus according to claim 17 wherein said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 19 (original): The robot apparatus according to claim 17 wherein said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 20 (original): The robot apparatus according to claim 15 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said erasure control means erasing said pre-set data from said storage means based on a pre-set transition state of said status transition model.

Claim 21 (original): The robot apparatus according to claim 13 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means depending on said pre-set behavior command or feeling information associated with said pre-set data.

Claim 22 (canceled)

Claim 23 (withdrawn): A furnishing medium for furnishing a program to a robot apparatus having a behavioral model outputting a pre-set behavior command or the feeling information, said program being adapted to execute processing including a step of outputting the pre-set behavior command or the feeling information based on said behavioral model or the feeling information based on the input information and a write control step of writing pre-set data based on said pre-set behavior command or the feeling information.

Claim 24 (currently amended): A robot apparatus having an instinct model for outputting the instinct information, said robot apparatus comprising:

detection means for detecting extraneous states, said detection means including extraneous data inputting means, wherein extraneous data is inputted by said extraneous data inputting means;

storage means for storing data; and

write control means for writing pre-set data in said storage means; wherein said write control means writes ~~writing~~ said pre-set data in said storage means based on said instinct information; and wherein said write control means writing the extraneous input data inputted as said pre-set data to said extraneous data input means in said storage means.

Claim 25 (canceled)

Claim 26 (original): The robot apparatus according to claim 24 wherein said behavioral model or said feeling model is a status transition model;

said write control means writing said pre-set data in said storage means based on a pre-set transition state of said status transition model.

Claim 27 (original): The robot apparatus according to claim 24 further comprising:

erasure control means for erasing pre-set data stored in said storage means;

said erasure control means erasing said pre-set data from said storage means based on said instinct information.

Claim 28 (original): The robot apparatus according to claim 24 further comprising:

erasure control means for erasing pre-set data stored in said storage means;

said write control means writing said pre-set data added to with the pre-set information derived from said instinct information in said storage means;

said erasure control means erasing said pre-set information from said storage means when the pre-set condition associated with the pre-set behavior command holds.

Claim 29 (original): The robot apparatus according to claim 28 wherein said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 30 (original): The robot apparatus according to claim 28 wherein said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 31 (original): The robot apparatus according to claim 26 further comprising:
erasure control means for erasing the pre-set data stored in said storage means;
said erasure control means erasing said pre-set data from said storage means based on a pre-set transition state of said status transition model.

Claim 32 (original): The robot apparatus according to claim 24 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means depending on said instinct information associated with said pre-set data.

Claim 33 (canceled)

Claim 34 (withdrawn): A furnishing medium for furnishing a program to a robot apparatus having an instinct model adapted to output the instinct information, said program being adapted to execute the processing including

an outputting step of outputting the instinct information by said instinct model based on the input information; and

a write control step of writing pre-set data in storage means based on said instinct information.

Claim 35 (withdrawn): A robot apparatus having a behavioral model, a feeling model or an instinct model changed based at least on inner factors, said behavioral model, feeling model or the instinct model outputting a pre-set behavior command, feeling information or the instinct information based on said inner factor, said robot apparatus comprising: monitoring means for monitoring the inner state as said inner factor; storage means for memorizing data; and

write control means for writing the pre-set data in said storage means;

said write control means writing said pre-set data in said storage means based on the monitored results by said monitoring means.

Claim 36 (withdrawn): The robot apparatus according to claim 35 further comprising:

erasure control means for erasing pre-set data stored in said storage means; said write control means writing said pre-set data added to with characteristics information on the inner state in said storage means;

said erasure control means erasing said pre-set data added to with characteristics information from said storage means when the pre-set condition associated with the characteristics information holds.

Claim 37 (withdrawn): The robot apparatus according to claim 36 wherein said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 38 (withdrawn): The robot apparatus according to claim 35 further comprising:

re-arraying means for re-arraying said pre-set data written in said storage means depending on said inner state associated with said pre-set data.

Claim 39 (canceled)

Claim 40 (withdrawn): A furnishing medium for furnishing a program to a robot apparatus having a behavioral model, a feeling model or an instinct model changed based at least on inner factors, said behavioral model, feeling model or the instinct model outputting a pre-set behavior command, feeling information or the instinct information based on said inner factor, said program causing execution of the processing including a write control step of monitoring the inner state as said inner factor to write pre-set data in storage means based on the monitored results.

Claim 41 (withdrawn): A display method comprising:

a read-out step of reading out said pre-set data memorized in said storage means by a robot apparatus having a behavioral model, a feeling model and/or an instinct model changed based at least on extraneous factors and/or inner factors, said robot apparatus writing pre-set data in storage means depending on conditions; and

a display step of displaying said pre-set data read out by said read-out step on a display.

Claim 42 (withdrawn): The display method according to claim 41 wherein said read-out step reads out from said storage means the extraneous input data as said pre-set data captured by said robot apparatus responsive to said condition.

Claim 43 (withdrawn): The display method according to claim 41 wherein said read-out step reads out a plurality of said pre-set data from said storage means and wherein said read-out step re-arrays said plural pre-set data to display the re-arrayed data.

Claim 44 (withdrawn): The display method according to claim 43 wherein said display step chronologically re-arrays the plural pre-set data depending on the time information added to said pre-set data to display the re-arrayed data in said display.

Claim 45 (withdrawn): The display method according to claim 41 further comprising:
an information outputting step of outputting the information associated with said pre-set data displayed in said display step.

Claim 46 (withdrawn): The display method according to claim 45 wherein the information outputting step outputs the letter information corresponding to said pre-set data.

Claim 47 (withdrawn): A furnishing medium for furnishing a program to a picture display apparatus adapted to demonstrate a picture on a display, said program being adapted to execute the processing including

a read-out step of reading out pre-set data stored in said storage means by a robot apparatus having a behavioral model and/or a feeling model and/or an instinct model changed depending on an extraneous factor or an inner factor, said robot apparatus writing pre-set data depending on conditions, and

a displaying step of displaying in said display said pre-set data read out by said read-out step.

Claim 48 (new): A robot apparatus having a behavioral model or a feeling model changed at least based on extraneous factors, comprising:

detection means for detecting extraneous states, said detection means includes extraneous data inputting means, wherein extraneous data is inputted in said extraneous data inputting means;

storage means for storing data; and

write control means for writing pre-set data in said storage means based on a detection signal detected by said detection means, wherein said write control means writes said extraneous input data to said extraneous data inputting means in said storage means.

Claim 49 (new): The robot apparatus according to claim 48 further comprising:

means for evaluating said detection signal;

said write control means writing said pre-set data in said storage means based on the evaluated results by said evaluation means.

Claim 50 (new): The robot apparatus according to claim 48 wherein said detection means includes pressure measurement means for measuring the pressure as the extraneous state, and wherein said evaluating means evaluates the pressure information as the detection signal from said pressure measurement means.

Claim 51 (new): The robot apparatus according to claim 48 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said write control means adding characteristics information of said detection signal to said pre-set data to write the resulting signal in said storage means;
said erasure control means erasing said pre-set data added to said characteristics information from said storage means when a pre-set condition consistent with the characteristics information holds.

Claim 52 (new): The robot apparatus according to claim 50 wherein said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 53 (new): The robot apparatus according to claim 50 wherein said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 54 (new): The robot apparatus according to claim 1 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means depending on a value of the detection signal associated with said pre-set data.

Claim 55 (new): A robot apparatus having a behavioral model or a feeling model changed at least based on extraneous factors, comprising:
detection means for detecting extraneous states;
storage means for storing data;
write control means for writing pre-set data in said storage means based on a detection signal detected by said detection means; and
erasure control means for erasing pre-set data stored in said storage means,
wherein said write control means adds characteristics information of said detection signal to said pre-set data to write the resulting signal in said storage means;
and wherein said erasure control means erases said pre-set data added to said characteristics information from said storage means when a pre-set condition consistent with the characteristics information holds.

Claim 56 (new): The robot apparatus according to claim 54 further comprising:
means for evaluating said detection signal,
wherein said write control means writes said pre-set data in said storage means based on
the evaluated results by said evaluation means.

Claim 57 (new): The robot apparatus according to claim 55 wherein said detection
means includes pressure measurement means for measuring the pressure as the extraneous state,
and wherein said evaluating means evaluates the pressure information as the detection signal
from said pressure measurement means.

Claim 58 (new): The robot apparatus according to claim 55 wherein said detection
means includes extraneous data inputting means, wherein extraneous data is inputted in said
extraneous data inputting means, and wherein said write control means writes extraneous input
data to said extraneous data inputting means in said storage means.

Claim 59 (new): The robot apparatus according to claim 55 wherein said pre-set
condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 60 (new): The robot apparatus according to claim 55 wherein said pre-set
condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 61 (new): The robot apparatus according to claim 1 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means
depending on a value of the detection signal associated with said pre-set data.

Claim 62 (new): A robot apparatus having a behavioral model or a feeling model
changed at least based on extraneous factors, comprising:
detection means for detecting extraneous states;
storage means for storing data;

write control means for writing pre-set data in said storage means based on a detection signal detected by said detection means; and

re-arraying means for re-arraying said pre-set data written in said storage means depending on a value of the detection signal associated with said pre-set data.

Claim 63 (new): The robot apparatus according to claim 62 further comprising:

means for evaluating said detection signal;

said write control means writing said pre-set data in said storage means based on the evaluated results by said evaluation means.

Claim 64 (new): The robot apparatus according to claim 62 wherein

said detection means includes pressure measurement means for measuring the pressure as the extraneous state;

said evaluating means evaluating the pressure information as the detection signal from said pressure measurement means.

Claim 65 (new): The robot apparatus according to claim 62 wherein

said detection means includes extraneous data inputting means at which extraneous data is inputted;

said write control means writing extraneous input data to said extraneous data inputting means in said storage means.

Claim 66 (new): The robot apparatus according to claim 62 further comprising:

erasure control means for erasing pre-set data stored in said storage means;

said write control means adding characteristics information of said detection signal to said pre-set data to write the resulting signal in said storage means;

said erasure control means erasing said pre-set data added to with said characteristics information from said storage means when a pre-set condition consistent with the characteristics information holds.

Claim 67 (new): The robot apparatus according to claim 66 wherein said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 68 (new): The robot apparatus according to claim 66 wherein said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 69 (new): A robot apparatus having a behavioral model for outputting a pre-set behavior command or a feeling model for outputting the feeling information, said robot apparatus comprising:

detection means for detecting extraneous states; storage means for storing data;
write control means for writing pre-set data in said storage means based on said pre-set behavior command or said feeling information; and
erasure control means for erasing pre-set data stored in said storage means, wherein said erasure control means erases said pre-set data from said storage means based on said pre-set behavior command or said feeling information.

Claim 70 (new): The robot apparatus according to claim 69 wherein
said detection means includes extraneous data inputting means at which
extraneous data is inputted;
said write control means writing extraneous input data to said extraneous data inputting means in said storage means.

Claim 71 (new): The robot apparatus according to claim 69 wherein
said behavioral model or said feeling model is a status transition model;
said write control means writing said pre-set data in said storage means based on a pre-set transition state of said status transition model.

Claim 72 (new): The robot apparatus according to claim 69 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said write control means writing said pre-set data added to with the pre-set information derived from said pre-set behavior command or the feeling information in said storage means;
said erasure control means erasing said pre-set information from said storage means when a pre-set condition associated with the pre-set behavior command holds.

Claim 73 (new): The robot apparatus according to claim 72 wherein
said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 74 (new): The robot apparatus according to claim 72 wherein
said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 75 (new): The robot apparatus according to claim 69 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said erasure control means erasing said pre-set data from said storage means based on a pre-set transition state of said status transition model.

Claim 76 (new): The robot apparatus according to claim 69 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means depending on said pre-set behavior command or feeling information associated with said pre-set data.

Claim 77 (new): A robot apparatus having a behavioral model for outputting a pre-set behavior command or a feeling model for outputting the feeling information, said robot apparatus comprising:
detection means for detecting extraneous states; storage means for storing data;

write control means for writing pre-set data in said storage means based on said pre-set behavior command or said feeling information; and

erasure control means for erasing pre-set data stored in said storage means,

wherein said write control means writes said pre-set data added to the pre-set information derived from said pre-set behavior command or the feeling information in said storage means;

and wherein said erasure control means erases said pre-set information from said storage means when a pre-set condition associated with the pre-set behavior command holds.

Claim 78 (new): The robot apparatus according to claim 77 wherein
said detection means includes extraneous data inputting means at which
extraneous data is inputted;
said write control means writing extraneous input data to said extraneous data inputting means in said storage means.

Claim 79 (new): The robot apparatus according to claim 77 wherein
said behavioral model or said feeling model is a status transition model;
said write control means writing said pre-set data in said storage means based on a pre-set transition state of said status transition model.

Claim 80 (new): The robot apparatus according to claim 77 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said erasure control means erasing said pre-set data from said storage means based on said pre-set behavior command or said feeling information.

Claim 81 (new): The robot apparatus according to claim 77 wherein
said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 82 (new): The robot apparatus according to claim 77 wherein said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 83 (new): The robot apparatus according to claim 77 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said erasure control means erasing said pre-set data from said storage means based on a pre-set transition state of said status transition model.

Claim 84 (new): The robot apparatus according to claim 77 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means depending on said pre-set behavior command or feeling information associated with said pre-set data.

Claim 85 (new): A robot apparatus having a behavioral model for outputting a pre-set status transition model for outputting the feeling information, said robot apparatus comprising:

detection means for detecting extraneous states; storage means for storing data;
write control means for writing pre-set data in said storage means based on said pre-set behavior command or said feeling information, wherein said write control means writes said pre-set data in said storage means based on a pre-set transition state of said status transition model;
and

erasure control means for erasing pre-set data stored in said storage means, wherein said erasure control means erases said pre-set data from said storage means based on a pre-set transition state of said status transition model.

Claim 86 (new): The robot apparatus according to claim 85 wherein
said detection means includes extraneous data inputting means at which
extraneous data is inputted;
said write control means writing extraneous input data to said extraneous data inputting
means in said storage means.

Claim 87 (new): The robot apparatus according to claim 85 further comprising:
erasure control means for erasing pre-set data stored in said storage means; said erasure
control means erasing said pre-set data from said storage means based on said pre-set behavior
command or said feeling information.

Claim 88 (new): The robot apparatus according to claim 85 further comprising:
erasure control means for erasing pre-set data stored in said storage means; said write
control means writing said pre-set data added to with the pre-set information derived from said
pre-set behavior command or the feeling information in said storage means;
said erasure control means erasing said pre-set information from said storage means when
a pre-set condition associated with the pre-set behavior command holds.

Claim 89 (new): The robot apparatus according to claim 88 wherein
said pre-set condition for said erasure control means is whether or not a pre-set value has
been reached.

Claim 90 (new): The robot apparatus according to claim 88 wherein
said pre-set condition for said erasure control means is whether or not a pre-set time has
elapsed.

Claim 91 (new): The robot apparatus according to claim 85 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means
depending on said pre-set behavior command or feeling information associated with said pre-set
data.

Claim 92 (new): A robot apparatus having a behavioral model for outputting a pre-set behavior command or a feeling model for outputting the feeling information, said robot apparatus comprising:
detection means for detecting extraneous states; storage means for storing data;
write control means for writing pre-set data in said storage means based on said pre-set behavior command or said feeling information; and
re-arraying means for re-arraying said pre-set data written in said storage means depending on said pre-set behavior command or feeling information associated with said pre-set data.

Claim 93 (new): The robot apparatus according to claim 92 wherein
said detection means includes extraneous data inputting means at which
extraneous data is inputted;
said write control means writing extraneous input data to said extraneous data inputting means in said storage means.

Claim 94 (new): The robot apparatus according to claim 92 wherein
said behavioral model or said feeling model is a status transition model;
said write control means writing said pre-set data in said storage means based on a pre-set transition state of said status transition model.

Claim 95 (new): The robot apparatus according to claim 92 further comprising:
erasure control means for erasing pre-set data stored in said storage means; said erasure control means erasing said pre-set data from said storage means based on said pre-set behavior command or said feeling information.

Claim 96 (new): The robot apparatus according to claim 92 further comprising:

erasure control means for erasing pre-set data stored in said storage means; said write control means writing said pre-set data added to with the pre-set information derived from said pre-set behavior command or the feeling information in said storage means;

said erasure control means erasing said pre-set information from said storage means when a pre-set condition associated with the pre-set behavior command holds.

Claim 97 (new): The robot apparatus according to claim 96 wherein

said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 98 (new): The robot apparatus according to claim 96 wherein

said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 99 (new): The robot apparatus according to claim 92 further comprising:

erasure control means for erasing pre-set data stored in said storage means;

said erasure control means erasing said pre-set data from said storage means based on a pre-set transition state of said status transition model.

Claim 100 (new): A robot apparatus having an instinct model for outputting the instinct information, said robot apparatus comprising:

detection means for detecting extraneous states;

storage means for storing data;

write control means for writing pre-set data in said storage means, wherein said write control means writing said pre-set data in said storage means based on said instinct information; and

erasure control means for erasing pre-set data stored in said storage means; said erasure control means erasing said pre-set data from said storage means based on said instinct information.

Claim 101 (new): The robot apparatus according to claim 100 wherein
said detection means includes an extraneous data inputting means in which extraneous
data is inputted;

said write control means writing the extraneous input data inputted as said pre-set data to
said extraneous data input means in said storage means.

Claim 102 (new): The robot apparatus according to claim 100 wherein
said behavioral model or said feeling model is a status transition model;
said write control means writing said pre-set data in said storage means based on a pre-set
transition state of said status transition model.

Claim 103 (new): The robot apparatus according to claim 100 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said write control means writing said pre-set data added to with the pre-set information
derived from said instinct information in said storage means;
said erasure control means erasing said pre-set information from said storage means when
a pre-set condition associated with the pre-set behavior command holds.

Claim 104 (new): The robot apparatus according to claim 103 wherein
said pre-set condition for said erasure control means is whether or not a pre-set value has
been reached.

Claim 105 (new): The robot apparatus according to claim 103 wherein
said pre-set condition for said erasure control means is whether or not a pre-set time has
elapsed.

Claim 106 (new): The robot apparatus according to claim 100 further comprising:

erasure control means for erasing the pre-set data stored in said storage means; said erasure control means erasing said pre-set data from said storage means based on a pre-set transition state of said status transition model.

Claim 107 (new): The robot apparatus according to claim 100 further comprising:

re-arraying means for re-arraying said pre-set data written in said storage means depending on said instinct information associated with said pre-set data.

Claim 108 (new): A robot apparatus having an instinct model for outputting the instinct information, said robot apparatus comprising:

detection means for detecting extraneous states;

storage means for storing data;

write control means for writing pre-set data in said storage means, wherein said write control means writes said pre-set data in said storage means based on said instinct information, and wherein said write control means writes said pre-set data added to the pre-set information derived from said instinct information in said storage means; and

erasure control means for erasing pre-set data stored in said storage means, wherein said erasure control means erases said pre-set information from said storage means when the pre-set condition associated with the pre-set behavior command holds.

Claim 109 (new): The robot apparatus according to claim 108 wherein

said detection means includes an extraneous data inputting means in which extraneous data is inputted;

said write control means writing the extraneous input data inputted as said pre-set data to said extraneous data input means in said storage means.

Claim 110 (new): The robot apparatus according to claim 108 wherein
said behavioral model or said feeling model is a status transition model;
said write control means writing said pre-set data in said storage means based on a pre-set
transition state of said status transition model.

Claim 111 (new): The robot apparatus according to claim 108 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said erasure control means erasing said pre-set data from said storage means based on
said instinct information.

Claim 112 (new): The robot apparatus according to claim 108 wherein
said pre-set condition for said erasure control means is whether or not a pre-set value has
been reached.

Claim 113 (new): The robot apparatus according to claim 108 wherein
said pre-set condition for said erasure control means is whether or not a pre-set time has
elapsed.

Claim 114 (new): The robot apparatus according to claim 108 further comprising:
erasure control means for erasing the pre-set data stored in said storage means; said
erasure control means erasing said pre-set data from said storage means based on a pre-set
transition state of said status transition model.

Claim 115 (new): The robot apparatus according to claim 108 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means
depending on said instinct information associated with said pre-set data.

Claim 116 (new): A robot apparatus having a status transition model for outputting the
instinct information, said robot apparatus comprising:
detection means for detecting extraneous states;

storage means for storing data; and

write control means for writing pre-set data in said storage means;

said write control means writing said pre-set data in said storage means based on said instinct information, wherein said write control means writes said pre-set data in said storage means based on a pre-set transition state of said status transition model; and

erasure control means for erasing the pre-set data stored in said storage means, wherein said erasure control means erases said pre-set data from said storage means based on a pre-set transition state of said status transition model.

Claim 117 (new): The robot apparatus according to claim 112 wherein

said detection means includes an extraneous data inputting means in which extraneous data is inputted;

said write control means writing the extraneous input data inputted as said pre-set data to said extraneous data input means in said storage means.

Claim 118 (new): The robot apparatus according to claim 116 further comprising:

erasure control means for erasing pre-set data stored in said storage means; said erasure control means erasing said pre-set data from said storage means based on said instinct information.

Claim 119 (new): The robot apparatus according to claim 119 further comprising:

erasure control means for erasing pre-set data stored in said storage means;

said write control means writing said pre-set data added to with the pre-set information derived from said instinct information in said storage means;

said erasure control means erasing said pre-set information from said storage means when a pre-set condition associated with the pre-set behavior command holds.

Claim 120 (new): The robot apparatus according to claim 119 wherein

said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 121 (new): The robot apparatus according to claim 116 wherein said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 122 (new): The robot apparatus according to claim 112 further comprising:
re-arraying means for re-arraying said pre-set data written in said storage means depending on said instinct information associated with said pre-set data.

Claim 123 (new): A robot apparatus having an instinct model for outputting the instinct information, said robot apparatus comprising:

detection means for detecting extraneous states;

storage means for storing data;

write control means for writing pre-set data in said storage means, wherein said write control means writes said pre-set data in said storage means based on said instinct information; and

re-arraying means for re-arraying said pre-set data written in said storage means depending on said instinct information associated with said pre-set data.

Claim 124 (new): The robot apparatus according to claim 123 wherein said detection means includes an extraneous data inputting means in which extraneous data is inputted;

said write control means writing the extraneous input data inputted as said pre-set data to said extraneous data input means in said storage means.

Claim 125 (new): The robot apparatus according to claim 123 wherein said behavioral model or said feeling model is a status transition model;
said write control means writing said pre-set data in said storage means based on a pre-set transition state of said status transition model.

Claim 126 (new): The robot apparatus according to claim 123 further comprising:
erasure control means for erasing pre-set data stored in said storage means; said erasure control means erasing said pre-set data from said storage means based on said instinct information.

Claim 127 (new): The robot apparatus according to claim 123 further comprising:
erasure control means for erasing pre-set data stored in said storage means;
said write control means writing said pre-set data added to with the pre-set information derived from said instinct information in said storage means;
said erasure control means erasing said pre-set information from said storage means when the pre-set condition associated with the pre-set behavior command holds.

Claim 128 (new): The robot apparatus according to claim 127 wherein
said pre-set condition for said erasure control means is whether or not a pre-set value has been reached.

Claim 129 (new): The robot apparatus according to claim 127 wherein
said pre-set condition for said erasure control means is whether or not a pre-set time has elapsed.

Claim 130 (new): The robot apparatus according to claim 123 further comprising:
erasure control means for erasing the pre-set data stored in said storage means; said erasure control means erasing said pre-set data from said storage means based on a pre-set transition state of said status transition model.